

Brake Motor 10W (□70mm)

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Motor Specification

Model	Output	Voltage	Frequency	Poles	Duty				Rated L	oad_		Capacitor		
Model 7BDG□-10G: Gear Type Shaft 7BDD□-10: D-Cut Type Shaft	W	Voltage	Hz	rules	Duty		Starting Torque kgfcm N.m		Current A	Torque		μF / VAC		
7BDGA-10G	10	1ø110	60	4	30min.	0.83	0.083	1550	0.31	0.70 0.0	70	3.5 / 250		
7BDGD-10G	10	1ø220	60	4	30min.	1.00	0.100	1550	0.20	0.79 0.0	79	1.2 / 450		
70005 400	10	1ø220	50	4	4	4	20:-	0.86	0.086	1050	0.16	0.82 0.0	82	1.0 / 450
7BDGE-10G	10	1ø240	50		30min.	0.99	0.099	1250	0.18	0.90 0.0	90	1.0 / 450		

- 1) Enter the phase & voltage code in the box (\Box) within the motor model name.
- 2) All models contain a built-in thermal protector.
- 3) Gear Type Shaft is for attaching Gearbox and D-Cut Type Shaft is for using motor only.

Max. Permissible Torque at Output Shaft of Gearbox

● 60Hz

IV	lotor Model	Gearbox Model	Gear Ratio	3	3.6	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
		Model	r/min	600	500	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
75	BDG□-10G	7GBK□BMH	kgfcm	2.0	2.4	3.9	4.9	5.9	8.2	9.8	11.8		17.8	19.3		32.2	40.3	48.3	50.0		50.0	
/'	sba⊔-ioa	/GBK BMIT	N.m	0.19	0.23	0.39	0.48	0.58	0.80	0.96	1.16	1.45	1.74	1.90	2.63	3.16	3.95	4.74	4.90	4.90	4.90	4.90

⊙ 50Hz

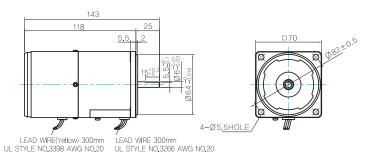
Motor Model	Gearbox Model	Gear Ratio	3	3.6	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
		r/min	500	416	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
7BDG□-10G	7GBK□BMH	kgfcm	2.0	2.5	4.1	5.1	6.1	8.5	10.2	12.3	15.4	18.5	20.1	27.9	33.5	41.8	50.0	50.0	50.0	50.0	50.0
/BDG=10G	/GDK L DWIT	Nm	0.20	0.24	0.40	0.50	0.60	0.83	1.00	1 20	1.51	1.81	1 97	2 73	3 28	4 10	4 90	4 90	4 90	4 90	4 90

- 1) Enter the phase & voltage code in the box (\Box) within the motor model name. 2) Enter the gear ratio in the box (\Box) within the Gearbox model name.
- 3) A colored background indicates gear shaft rotation in the same direction as the motor shaft; a white background indicates rotation in the opposite direction.
- 4) The rotating speed is calculated by dividing the motor's synchronous speed (50Hz: 1,500r/min, 60Hz: 1,800r/min) by the gear ratio. The actual speed is 2~20% less than the displayed value, depending on the size of the load.

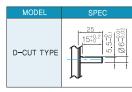
Dimensions

MOTOR ONLY

● MOTOR MODEL: 7BDD□-10 (NO FAN)



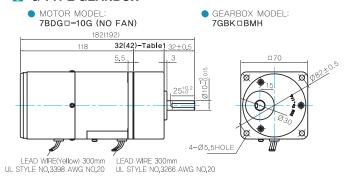
MOTOR OUTPUT SHAFT





GEARED MOTOR

G TYPE GEARBOX



GEARBOX OUTPUT SHAFT

MODEL	SPEC
KEY TYPE	32 25+0.2 25+0.2 00 00 00 00 00 00 00 00 00 00 00 00 00

KEY SPEC

	GEA	RBOX	
4+0	2.5 +0 1	25±0.5 9 9	4_0,03

WEIGHT

	PART	WEIGHT(Kg)
	MOTOR	1,3
	7GBK3BMH - 7GBK18BMH	0.36
GEAR BOX	7GBK25BMH - 7GBK30BMH	0.44
	7GBK36BMH - 7GBK180BMH	0.5

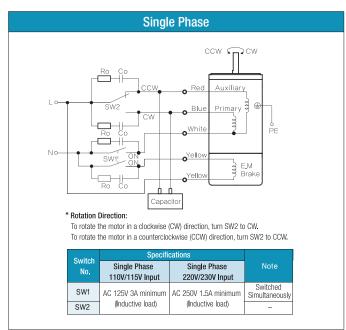
32(42)-Table1

SIZE(mm)	GEAR RATIO
32	7GBK3BMH - 7GBK18BMH
42	7GBK25BMH - 7GBK180BMH

Motor Images



(iii) Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) SW1 operates both motor and electromagnetic brake action.
- 4) The electromagnetic brake will be released and the motor will rotate when SW1 is switched simultaneously to ON. When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load. 5) If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (yellow). 6) Ro and Co indicate CR circuit for surge suppression. [Ro= $5\sim200\Omega$, Co= $0.1\sim0.2\mu$ F, 200W (400W)]